

MIMO-OFDM Wireless Communications with MATLAB[®]

Chapter 1. The Wireless Channel : Propagation and Fading

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Chapter 1. Kablosuz Kanal : Yayılım ve Sönümlenme

- **Reflection:** Yansıma (binalar, yer vs.)
- **Diffraction** Kırınım (yüzeylerde keskin düzensizlikler veya küçük açıklıklar.)
- **Scattering** Saçılım (trafik işaretleri, lambalar, vs.)
- **Fading** Sönümlenme → Çok yollu (multipath)
→ Gölgeleme (shadowing)
- **Multipath fading**
- **Shadowing**
 - HF 3-30 MHz
 - UHF 300-3000 GHz
 - SHF 3-30 GHz
 - 4G LTE, 5G, 3G, 2G
↓ MHz
800-2.5 GHz
 - 5G (çok geniş olacak)
3.5 GHz 28 GHz
 - UMTS GSM

Chapter 1. Kablosuz Kanal : Yayılım ve Sönümlenme

- 1.1 LARGE-SCALE FADING (mesafe ile alakalı, gölgelenme ile alakalı)
 - 1.1.1 General Path Loss Model → yol kaybı
 - 1.1.2 Okumura/Hata Model
 - 1.1.3 IEEE 802.16d Model
- 1.2 SMALL-SCALE FADING (multipath,
 - 1.2.1 Parameters for Small-Scale Fading
 - 1.2.2 Time-Dispersive vs. Frequency-Dispersive Fading
 - 1.2.3 Statistical Characterization and Generation of Fading Channel

Chapter 1. Kablosuz Kanal

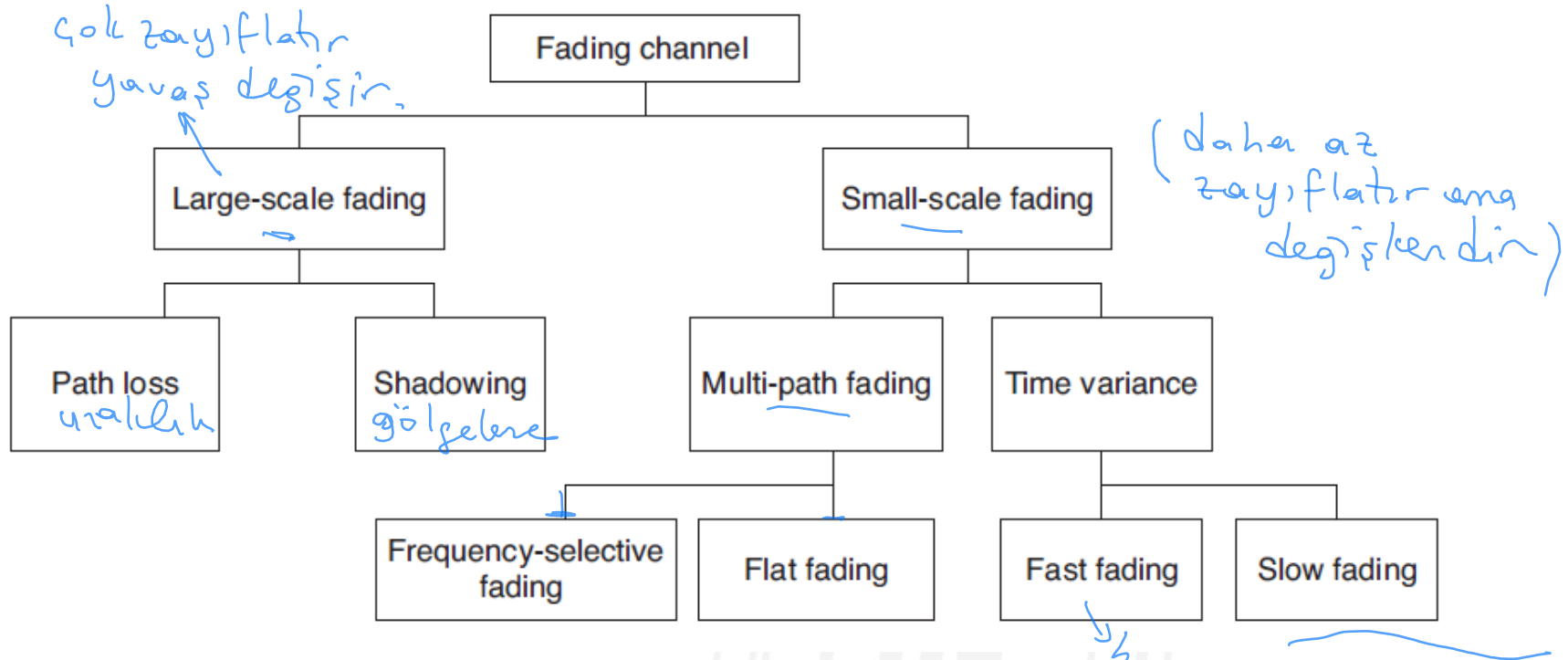


Figure 1.1 Sönümlü Kanalların Sınıflandırması

Chapter 1. Kablosuz Kanal

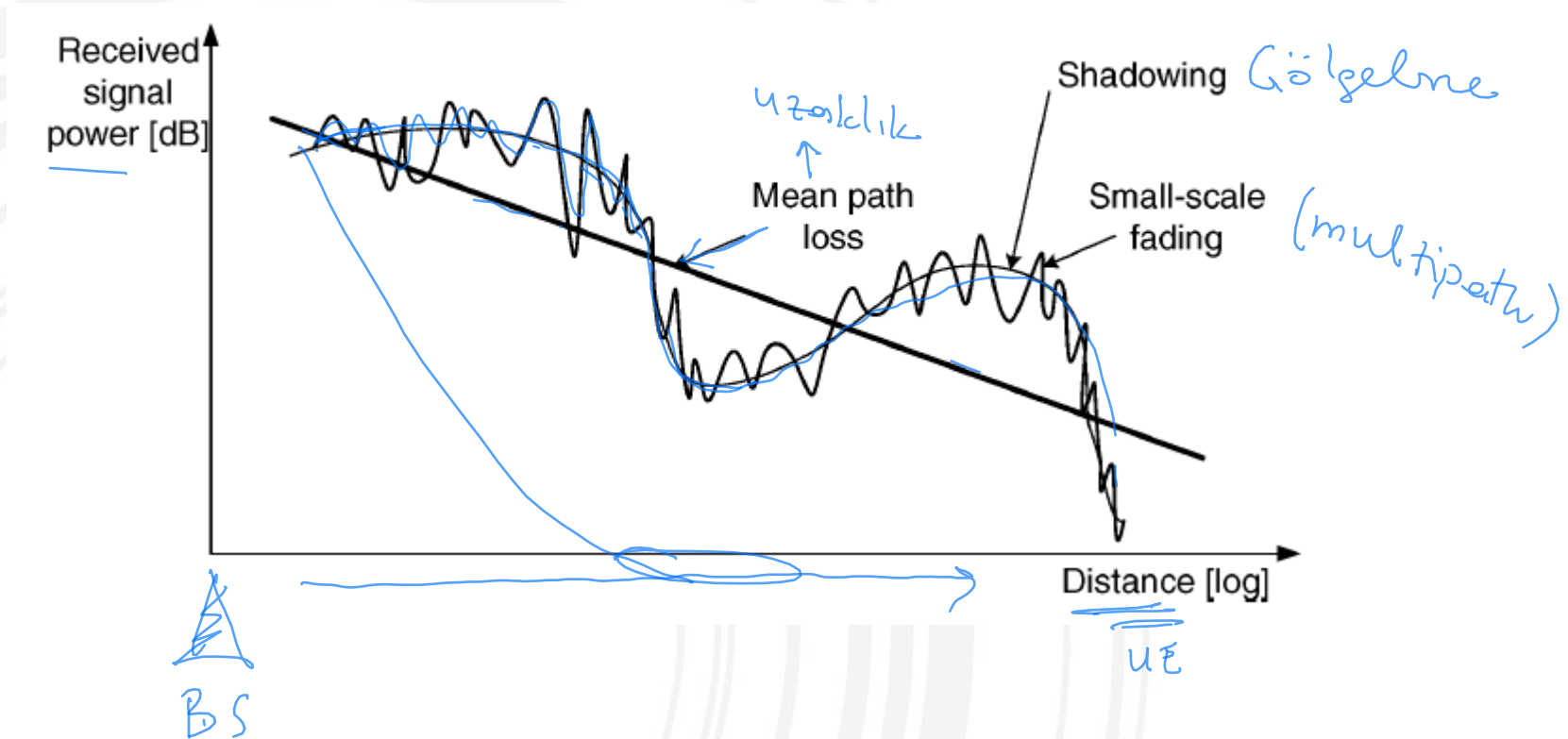


Figure 1.2 Large-scale fading vs. small-scale fading

Chapter 1. Kablosuz Kanal

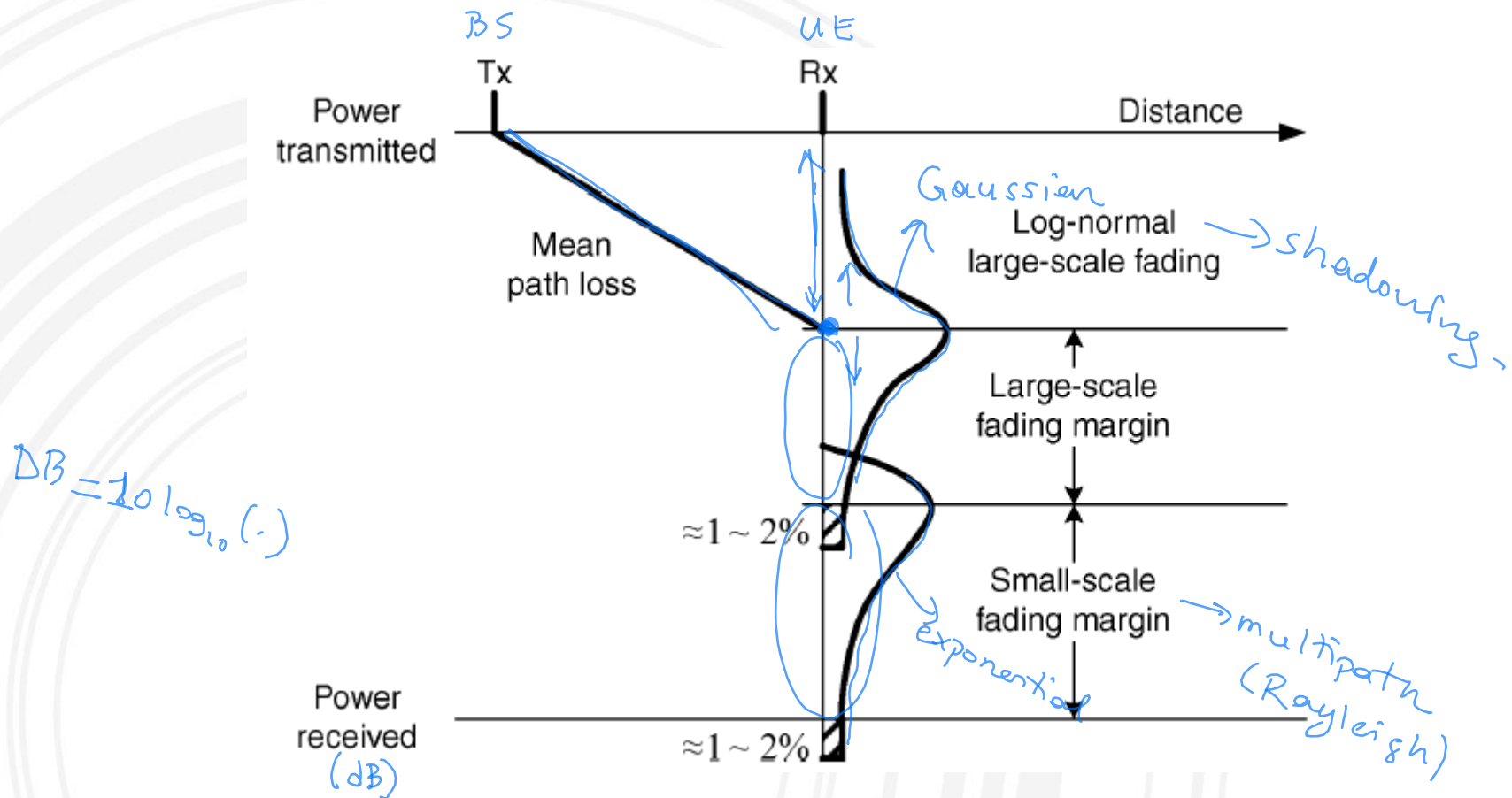


Figure 1.3 Link budget for the fading channel(1994 IEEE. Reproduced from Greenwood, D. and Hanzo, L., "Characterization of mobile radio channels," in Mobile Radio Communications, R. Steele(ed.), pp. 91–185,1994, with permission from Institute of Electrical and Electronics Engineers (IEEE).)

1.1 Büyük Çaplı Sönümlenme

1.1.1 Genel Yol Kaybı Modeli

Friis denklemini

(Path Loss)

$$\lambda = \frac{c}{f} = \frac{3 \times 10^8}{2.4 \times 10^9} = \frac{1}{10} \text{ metre} \quad \text{WiFi } 2.4 \text{ GHz} = f$$

trans pow. → tx ant gain → rx ant gain → dalga boyu → donanımdaki kayıplar. → uzaklık

$$P_r(d) = \frac{P_t G_t G_r \lambda^2}{(4\pi)^2 d^2 L}$$

received power



(1.1)

$$PL_F(d)[dB] = 10 \log_{10} \left(\frac{P_t}{P_r} \right) = -10 \log_{10} \left(\frac{G_t G_r \lambda^2}{(4\pi)^2 d^2} \right)$$

(1.2)

→

$$PL_F(d)[dB] = 10 \log_{10} \left(\frac{P_t}{P_r} \right) = -10 \log_{10} \left(\frac{\lambda^2}{(4\pi)^2 d^2} \right)$$

antenn kazanç olmadan

(1.3)

$$PL_F = 20 \log_{10} \left(\frac{4\pi d}{\lambda} \right) \rightarrow \text{free space pathloss.}$$

1.1.1 Genel Yol Kaybı Modeli

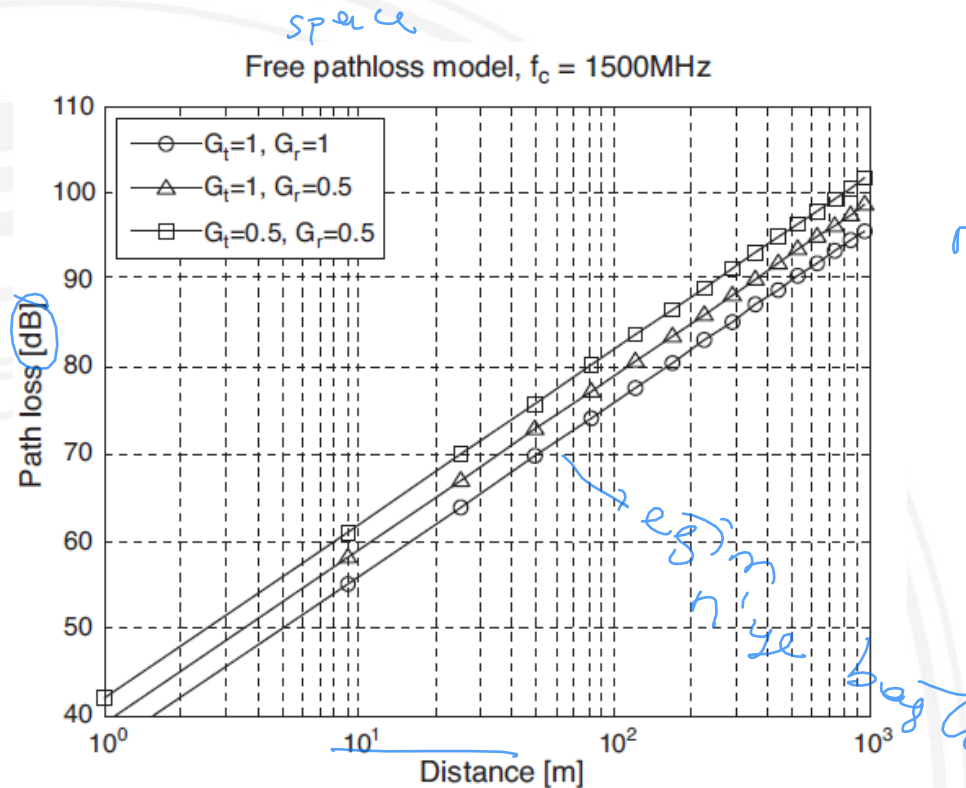


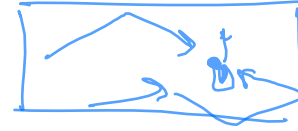
Figure 1.4 Free-space path loss model

$$PL_{LD}(d)[dB] = PL_F(d_0) + 10n \log_{10} \left(\frac{d}{d_0} \right) \quad (1.4)$$

Handwritten blue notes: refers, log distance

1.1.1 Genel Yol Kaybı Modeli

urban: şehir içi



Environment	Path Loss Exponent ()
Free Space	★ 2
Urban area cellular radio	2.7 to 3.5
<u>Shadowed</u> urban cellular radio	3 to 5
In building Line-Of-Sight	<u>1.6 to 1.8</u>
Obstructed in building	4 to 6
Obstructed in factories	2 to 3

Table 1.1 Path loss exponent [2].

1.1.1 Genel Yol Kaybı Modeli

X_σ : shadowing
(log-normal)
distributed
dB değeri
Gauss dağılımı
 $X_\sigma \sim \mathcal{N}(0, \sigma)$

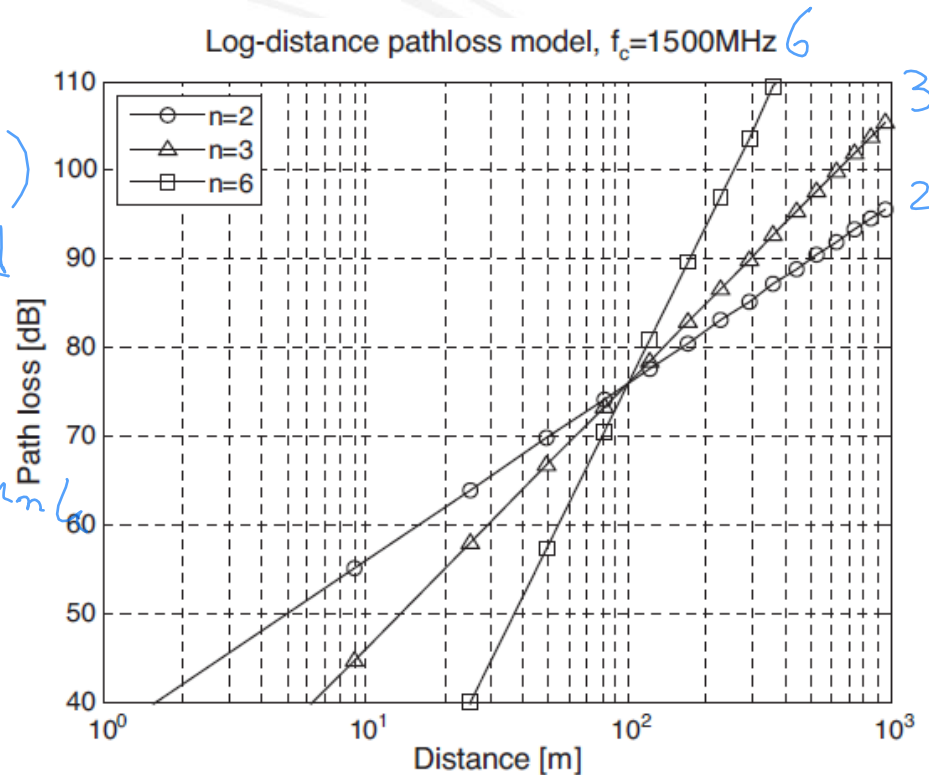


Figure 1.5 Log-distance pathloss model

$$PL(d)[dB] = \overline{PL}(d) + X_\sigma = \overline{PL}_F(d_0) + 10n \log\left(\frac{d}{d_0}\right) + X_\sigma \quad (1.5)$$

1.1.1 Genel Yol Kaybı Modeli

$$X_{\sigma} = \mathcal{N}(0, 3)$$

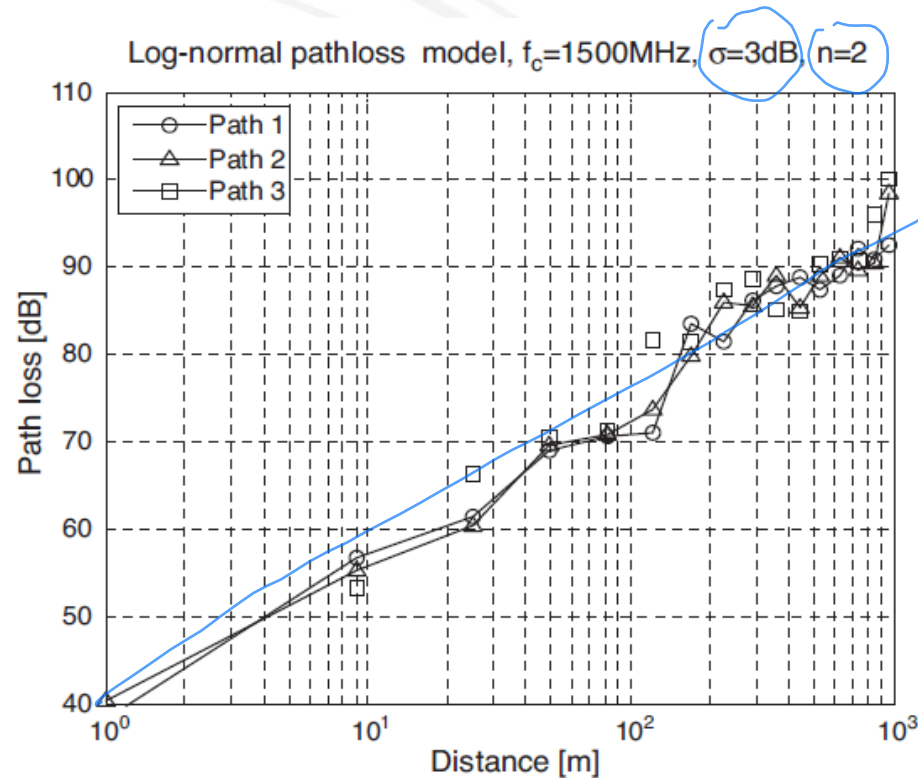


Figure 1.6 Log-normal shadowing path loss model

1.1.2 Okumura/Hata Modeli

(dereysel modeller)
dereyler sonucunda

Okum: 500 MHz — 1500 MHz
 $f_c \leq d < 100 \text{ km}$
 $30 \text{ m} < h_{Tx} < 1000 \text{ m}$

$$PL_{Ok}(d)[\text{dB}] = PL_F + A_{MU}(f, d) - G_{Rx} - G_{Tx} + G_{AREA} \quad (1.6)$$

free space
 medium attenuation factor
 ant → ant → environment gain

$$PL_{Hata,U}(d)[\text{dB}] = 69.55 + 26.16 \log f_c - 13.82 \log h_{Tx} - C_{Rx} + (44.9 - 6.55 \log h_{Tx}) \log d \quad (1.7)$$

urban
 carrier free (MHz)
 height
 correlation coeff
 height
 Hata urban suburban open area

$$C_{Rx} = 0.8 + (1.1 \log f_c - 0.7) h_{Rx} - 1.56 \log f_c$$

(küçük - orta kapsama alanı)
 carrier (MHz)
 rx height
 carrier (MHz)

(1.8)

1.1.2 Okumura/Hata Modeli

büyük kapsama
↓

$$C_{Rx} = \begin{cases} 8.29(\log(1.54h_{Rx}))^2 - 1.1 & \text{if } 150\text{MHz} \leq f_c \leq 200\text{MHz} \\ 3.2(\log(11.75h_{Rx}))^2 - 4.97 & \text{if } 200\text{MHz} \leq f_c \leq 1500\text{MHz} \end{cases} \quad (1.9)$$

← GSM, 3G

$$PL_{Hata,SU}(d)[dB] = \underbrace{PL_{Hata,U}(d)}_{\text{urban}} - 2\left(\log \frac{f_c}{28}\right)^2 - 5.4 \quad (1.10)$$

→ suburban (daha az kısıp)

$$PL_{Hata,O}(d)[dB] = PL_{Hata,U}(d) - 4.78(\log f_c)^2 + 18.33\log f_c - 40.97 \quad (1.11)$$

→ open area

1.1.2 Okumura/Hata Modeli

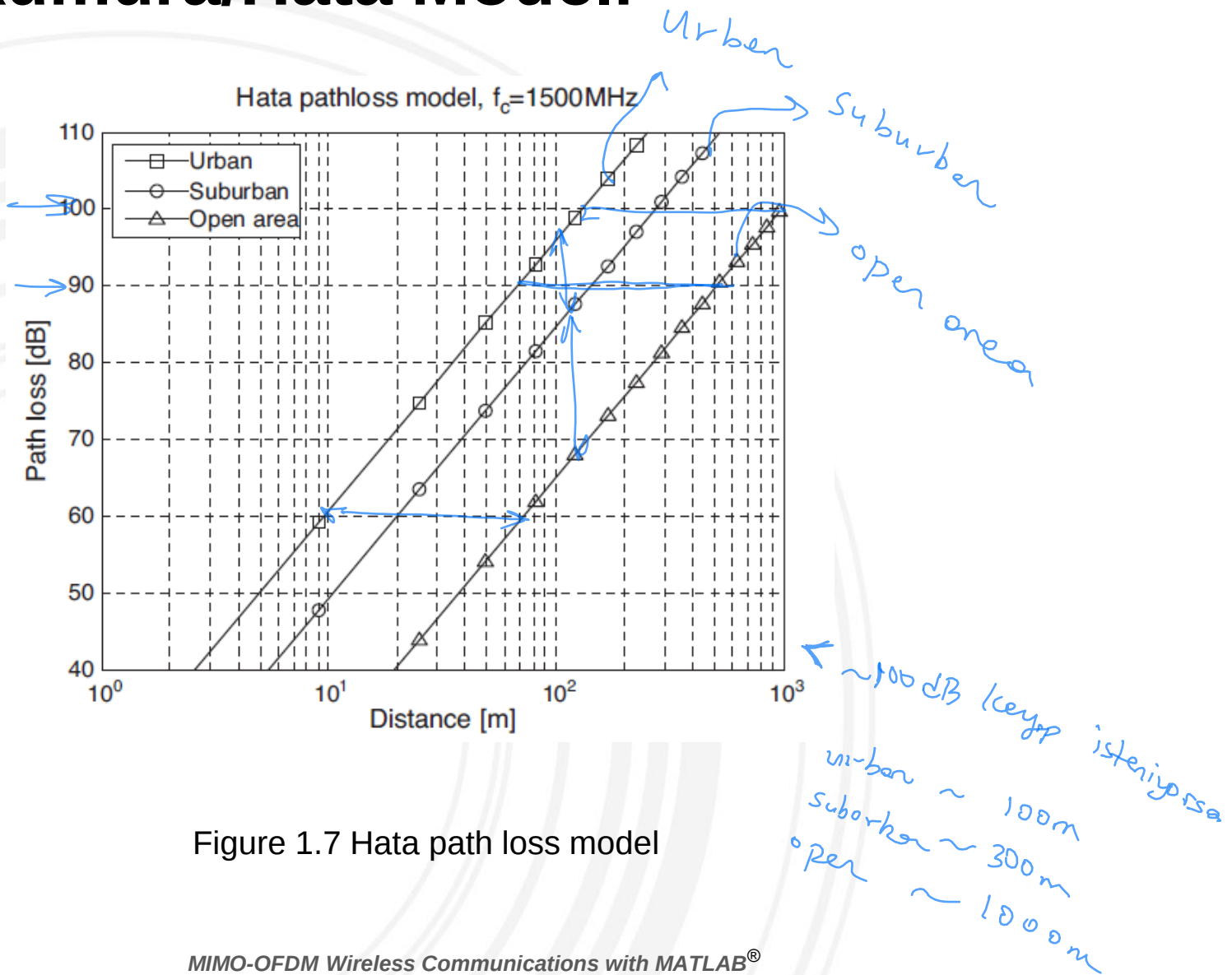


Figure 1.7 Hata path loss model

1.1.3 IEEE 802.16d (WiMax)

fixed → 11 GHz

→ 802.16e (mobile WiMax)

$$PL_{802.16}(d)[dB] = PL_F(d_0) + 10\gamma \log_{10}\left(\frac{d}{d_0}\right) + C_f + C_{Rx} \quad \text{for } d > d_0 \quad (1.12)$$

free s. d_0 exponent boom correction coeff

$$C_f = 6 \log_{10}(f_c / 2000)$$

MHz

$$\gamma = a - b h_{Tx} + \frac{c}{h_{Tx}}$$

802.16d
A
B
C (1.13)

$$C_{Rx} = \begin{cases} -10.8 \log_{10}(h_{Rx} / 2) & \text{for Type A and B} \\ -20 \log_{10}(h_{Rx} / 2) & \text{for Type C} \end{cases}$$

AT&T ölçümleri

(1.14)

Rx coeff

$$C_{Rx} = \begin{cases} -10 \log_{10}(h_{Rx} / 3) & \text{for } h_{Rx} \leq 3m \\ -20 \log_{10}(h_{Rx} / 3) & \text{for } h_{Rx} > 3m \end{cases}$$

Okumura ölçümleri

(1.15)

IEEE 802.11 Wi-Fi
IEEE 802.3 Ethernet
802.14 Bluetooth
802.15 ZigBee

1.1.3 IEEE 802.16d

Parameter	Type A	Type B	Type C
a	4.6	4	3.6
b	0.0075	0.0065	0.005
c	12.6	17.1	20

Table 1.2 Types of IEEE 802.16d path loss models.

Macro cell suburban ART $\rightarrow$ BRT
hilly terrain, moderate
tree density
M C sub-ART $\rightarrow$ BRT
intermediate
Path loss

MC suburban
ART $\rightarrow$ BRT
flat terrain
light tree
density

1.1.3 IEEE 802.16d

Parameter	Type A	Type B	Type C
a	4.6	4	3.6
b	0.0075	0.0065	0.005
c	12.6	17.1	20

Table 1.3 Parameters for IEEE 802.16d type A, B, and C models.

1.1.3 IEEE 802.16d

$$20\log_{10}\left(\frac{4\pi d'_0}{\lambda}\right) = 20\log_{10}\left(\frac{4\pi d_0}{\lambda}\right) + 10\gamma\log_{10}\left(\frac{d'_0}{d_0}\right) + C_f + C_{Rx} \quad (1.16)$$

$$d'_0 = d_0 10^{-\left(\frac{C_f + C_{Rx}}{10\gamma}\right)} \quad (1.17)$$

$$PL_{M802.16}(d)[dB] = \begin{cases} 20\log_{10}\left(\frac{4\pi d}{\lambda}\right) & \text{for } d \leq d'_0 \\ 20\log_{10}\left(\frac{4\pi d'_0}{\lambda}\right) + 10\gamma\log_{10}\left(\frac{d}{d'_0}\right) + C_f + C_{Rx} & \text{for } d > d'_0 \end{cases} \quad (1.18)$$

1.1.3 IEEE 802.16d

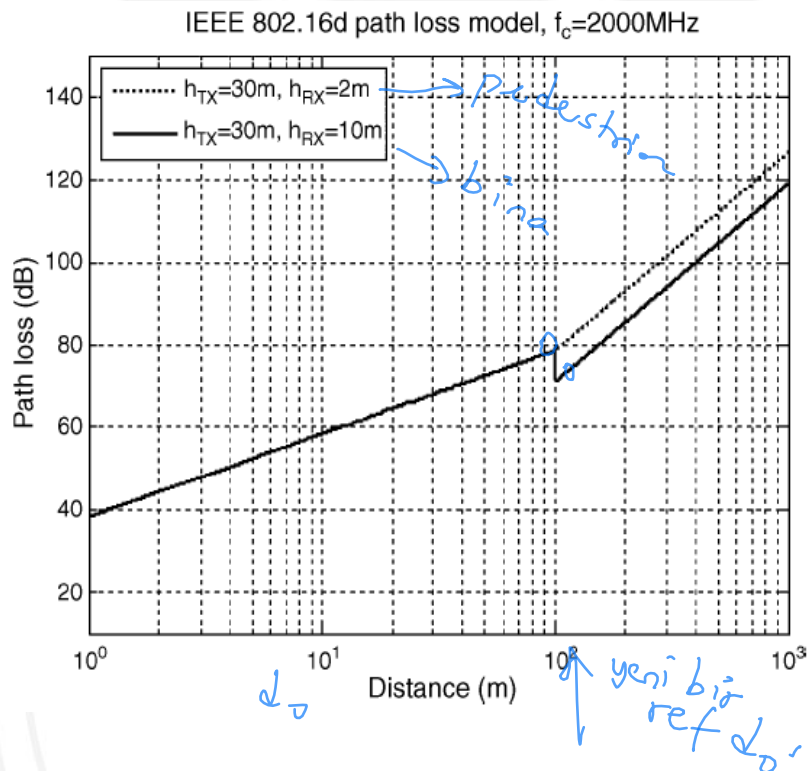


Figure 1.8 IEEE 802.16d path loss model

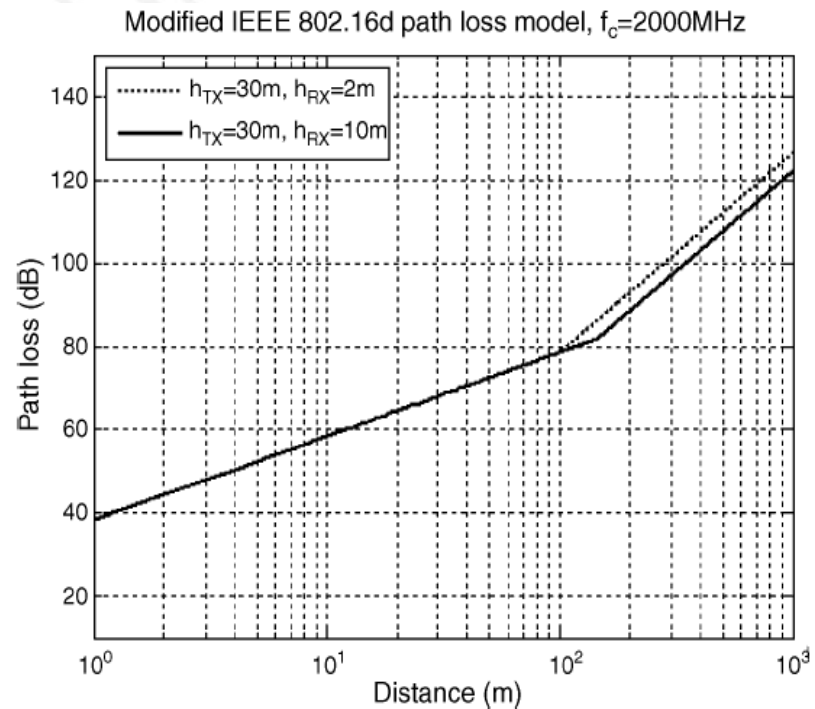


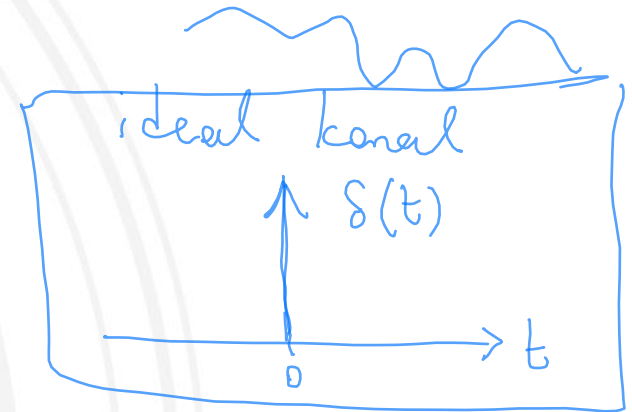
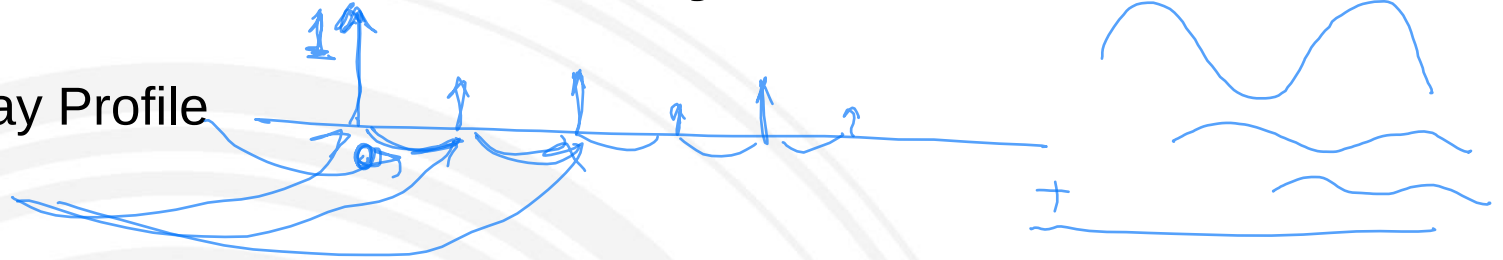
Figure 1.9 Modified IEEE 802.16d path loss model

1.2 Küçük Çaplı Sönümlenme

fading

1.2.1 Zaman ve Frekans Yayılmalı Sönümlenme

- Power Delay Profile
- Tap (Dal)
- Relative Delay
- Relative average power
- Mean excess delay (1. tap'a göre ort. gecikme)
- RMS Delay Spread (root mean square)



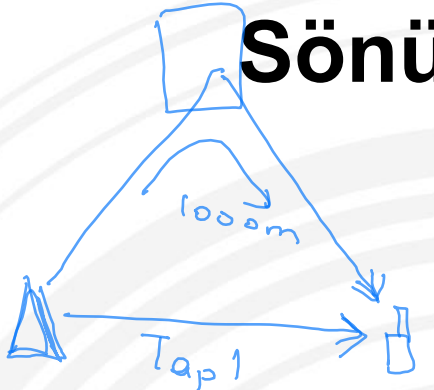
(a) Frequency-non-selective fading channel



(b) Frequency-selective fading channel

birkaç ms'n için
time-invariant
varsayıyoruz.
modele göre
deterministik.

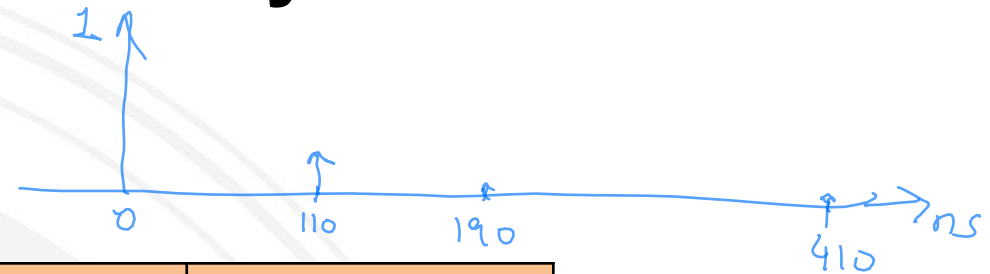
1.2.1 Zaman ve Frekans Yayımlı Sönümlenme



1000m fazlader

$$\frac{1000}{3 \times 10^8} = 10^{-6} \frac{10}{3} = 3.3 \mu s$$

$$\frac{10}{3 \times 10^8} = \frac{100 \times 10^{-9}}{3} = 33 ns$$



Tap	Relative delay (ns)	Average Power (dB)
1	0	(0.0
2	110	(-9.7
3	190	(-19.2
4	410	(-22.8

Table 1.4 Power delay profile: example (ITU-R Pedestrian A Model).

Yaya

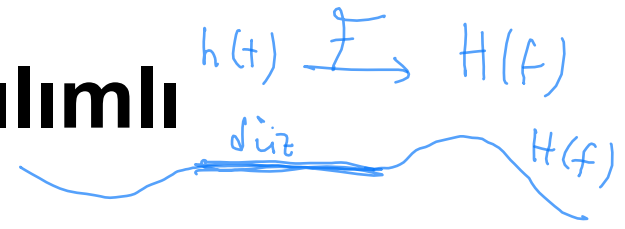
1.2.1 Zaman ve Frekans Yayımlı Sönümlenme

■ Düz sönümlenme

$$B_S \ll B_C$$

$$T_S \gg \sigma_\tau$$

(1.19)

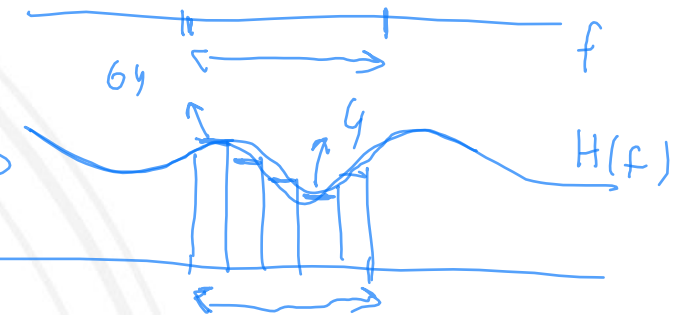


■ Frekans seçici sönümlenme

$$B_S > B_C$$

$$T_S > \sigma_\tau$$

(1.20)



ort

$$\bar{\tau} = \frac{\sum_k a_k^2 \tau_k}{\sum_k a_k^2} = \frac{\sum_k P(\tau_k) \tau_k}{\sum_k P(\tau_k)}$$

Mean excess delay (1.21)

$$\sigma_\tau = \sqrt{\tau^2 - (\bar{\tau})^2}$$

RMS Delay Spread

(1.22)

std sapma

kare ort

$$\tau^2 = \frac{\sum_k a_k^2 \tau_k^2}{\sum_k a_k^2} = \frac{\sum_k P(\tau_k) \tau_k^2}{\sum_k P(\tau_k)}$$

(1.23)

τ_k : relative delay of the k th path

1.2.1 Time-Dispersive vs. Frequency-Dispersive Fading

ϕ 0.9 0.5
 indoor ~ 100 ns $\rightarrow B_c$ 10M 200kHz 2MHz
 outdoor ~ 1000 ns $\rightarrow B_c$ 1MHz 20kHz 200kHz
 ✓

- $$B_c \approx \frac{1}{\sigma_\tau} \quad \text{Tutarlılık Bandı} \quad \text{Coherence bandwidth} \quad (1.24)$$

- $$B_c \approx \frac{1}{50\sigma_\tau} \quad \text{0.9 ilintili tutarlılık bandı} \quad (1.25)$$

çok düşük bir sönmülme için

- $$B_c \approx \frac{1}{5\sigma_\tau} \quad \text{0.5 ilintili tutarlılık bandı} \quad (1.26)$$

- $$\begin{aligned} \text{Hızlı sönmülme} \quad T_s > T_c \\ B_s > B_D \end{aligned} \quad (1.27)$$

- $$\begin{aligned} \text{Yavaş sönmülme} \quad T_s \ll T_c \\ B_s \gg B_D \end{aligned} \quad (1.28)$$

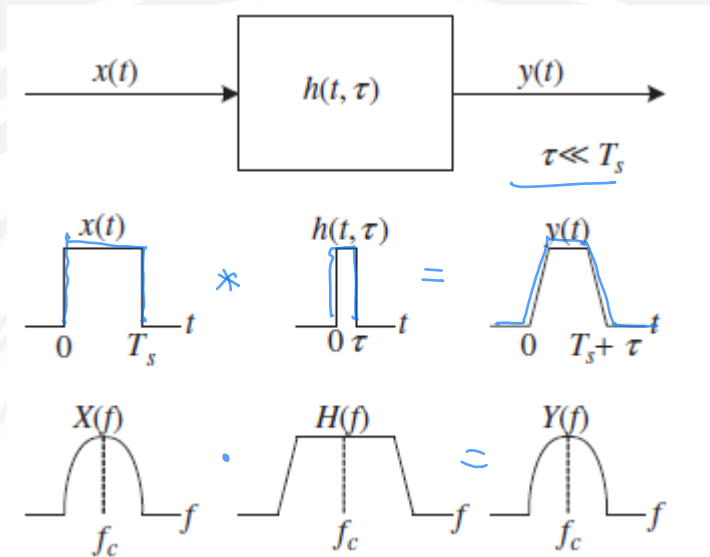
açık alanda tek
 tük yüksek
 binalar varsa
 σ_τ yüksektir.

1.2 Küçük Çaplı Sönümlenme

1.2.1 Zaman ve Frekans Yayılımlı Sönümlenme

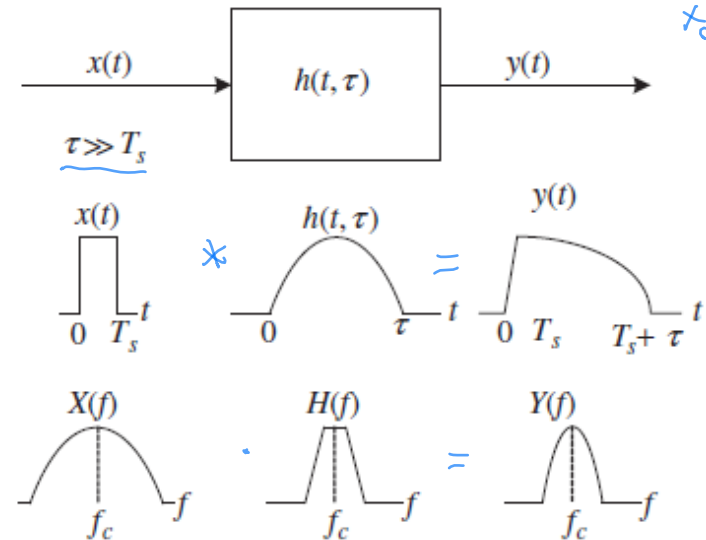
T_s : sembol süresi τ : saçılım süresi
 $\rightarrow$ tasarlayabilirim $\rightarrow$ kontrol edenim

pratikte, günümüzde
 $T_s > \tau$ olacak şekilde tasarlanır.



(a) Frequency-non-selective fading channel

flat fading



(b) Frequency-selective fading channel

Figure 1.10 Characteristics of fading due to time dispersion over multi-path channel

1.2.1 Zaman ve Frekans Yayılımlı Sönümlenme

frekansdaki
sağılım
↓
Doppler

Alıcı veya verici hareket halindeyse → Bağıl hız
 $f_m = \frac{v}{c} f_c \rightarrow$ taşıyıcı freq.

■ Tutarlılık zamanı $T_C \approx \frac{1}{f_m}$

$B_D = 2 f_m$

(1.29) Doppler kayması

$f_m = \frac{v}{\lambda} \rightarrow$ dalga boyu

■ Tutarlılık zamanı $T_C \approx \frac{9}{16\pi f_m}$

→ 0.5 ilinti

(1.30)

$f_m \uparrow \Rightarrow T_C \downarrow$
Tutarlılık zamanı

■ Tutarlılık zamanı $T_C = \sqrt{\frac{9}{16\pi f_m^2}} = \frac{0.423}{f_m}$

sık kullanılır. (1.31)

$v = 3 \text{ m/s}$ yaya
 $f_m = \frac{3}{3 \times 10^8} \times 20 \times 10^8 = 20 \text{ Hz}$
 $T_C = \frac{0.423}{20} \approx 21 \text{ ms}$

$v = 100 \text{ m/s}$ $f_c = 2 \text{ GHz}$
 $f_m = \frac{100}{3 \times 10^8} \times 20 \times 10^8 = 667 \text{ Hz}$

$\frac{0.423}{667} = 0.6 \text{ ms}$
Gök hızı desisen

1.2.3 Statistical Characterization and Generation of Fading Channel

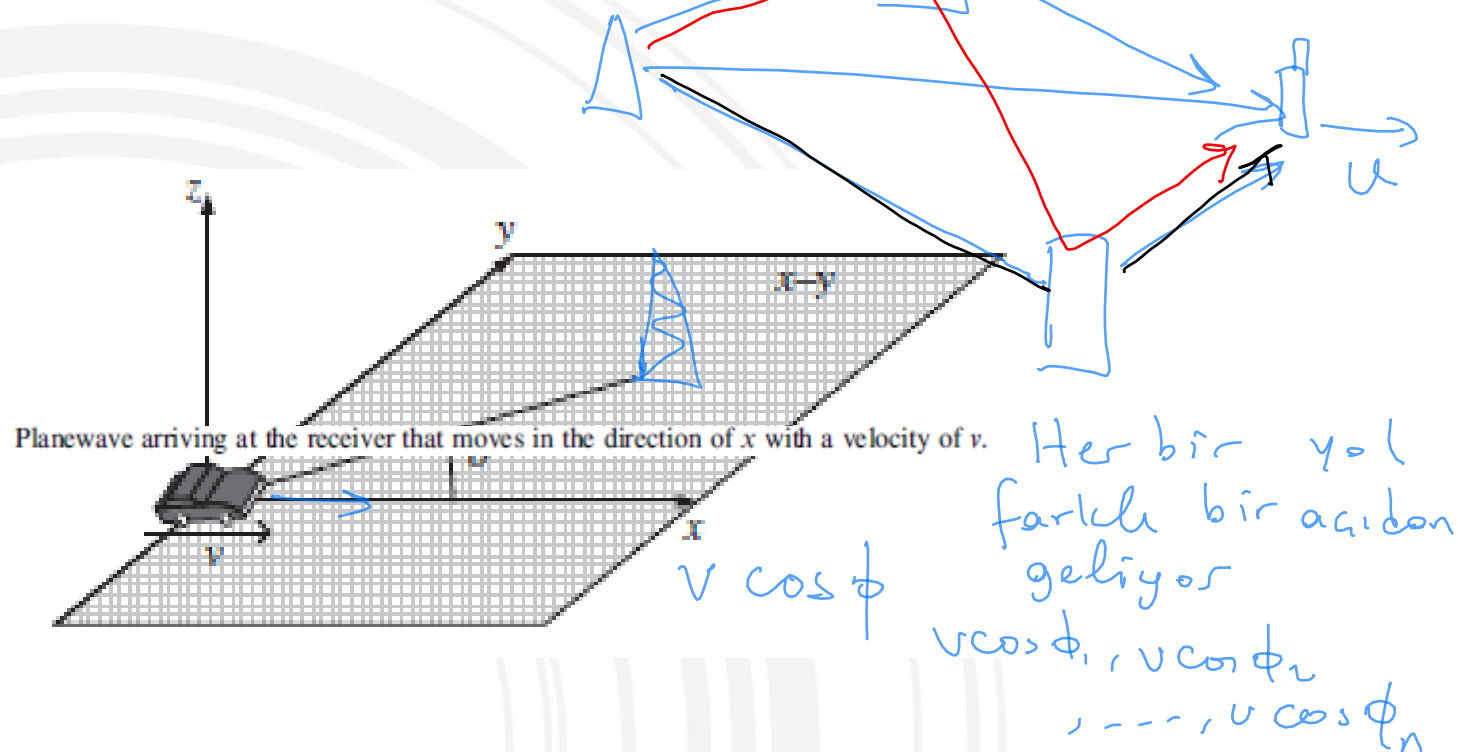


Figure 1.11 Planewave arriving at receiver moves in the direction of x with a velocity of v

1.2.3 Sönümlü Kanalin İstatistiksel Karakterizasyonu ve Üretimi

- Alıcıdaki sinyal

Baseband

$$y(t) = \sum_{i=1}^I C_i e^{-j\phi_i(t)} x(t - \tau_i)$$

passband: $\tilde{y}(t) = \text{Re} \left[\sum_{i=1}^I C_i e^{j2\pi(f_c + f_i)(t - \tau_i)} x(t - \tau_i) \right]$
 $= \text{Re} \left[y(t) e^{j2\pi f_c t} \right]$

$$\phi_i(t) = 2\pi \left\{ (f_c + f_i) \tau_i - f_i \right\} \quad (1.35)$$

- Kanal modeli

(impulse response)

$$h(t, \tau) = \sum_{i=1}^I C_i e^{-j\phi_i(t)} \delta(t - \tau_i)$$

$\delta(t)$ Dirac delta func

$$f_i = f_m \cos \theta_i$$

$\downarrow$
 $\frac{v}{\lambda}$ $\rightarrow$ $a_{\xi, s}$

(1.36)

- Yol gecikmesi sembol zamanından kısaysa

$$h(t, \tau) = \sum_{i=1}^I C_i e^{-j\phi_i(t)} \delta(t - \hat{\tau}) = h(t) \delta(t - \hat{\tau})$$

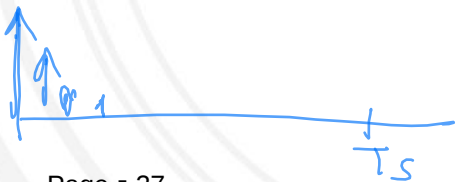
much less

$$\tau_i \ll T_s \quad \forall i$$

$$\text{no intersymbol interference} \quad (1.37)$$

$$\tau_i \approx \hat{\tau} \quad \forall i \text{ alınız}$$

$$h(t) = \sum_{i=1}^I C_i e^{-j\phi_i(t)}$$



1.2.3 Sönümlü Kanalin İstatistiksel Karakterizasyonu ve Üretimi

$x(t)=1$ olursa $\tilde{y}(t) = \text{Re}[y(t) e^{j2\pi f_c t}]$

$$\tilde{y}(t) = h_I(t) \cos 2\pi f_c t - h_Q(t) \sin 2\pi f_c t$$

$$h(t) = h_I(t) + j h_Q(t) \quad (1.38)$$

$\rightarrow$ $h_I(t) = \sum_{i=1}^I C_i \cos \phi_i(t)$ *soluk sayı da ve rastgele sayılar ve bağımsız $\rightarrow$ Central Limit Theorem*
in phase
 $\phi_i \in [0, 2\pi]$ uniform

$\rightarrow$ $h_Q(t) = \sum_{i=1}^I C_i \sin \phi_i(t)$ *quadrature*

▪ Rayleigh dağılımlı olarak modellenebilir

$$\gamma_{\tilde{y}\tilde{y}}(\tau) = E[\tilde{y}(t)\tilde{y}(t+\tau)]$$

$$= E[h_I(t)h_I(t+\tau)] \cos 2\pi f \tau - E[h_Q(t)h_I(t+\tau)] \sin 2\pi f \tau$$

$$= \gamma_{h_I h_I}(\tau) \cos 2\pi f_c \tau - \gamma_{h_I h_Q}(\tau) \sin 2\pi f_c \tau$$

$$(1.41)$$

Rayleigh
Sönümlenmesi

$y(t) = \sqrt{h_I^2(t) + h_Q^2(t)} = \sqrt{h_I^2 + h_Q^2}$ *Gauss dağılımlı varsayılır.*
 $E\{h_I^2(t)\} + E\{h_Q^2(t)\} = \sum_{i=1}^I C_i^2$
Rayleigh dağılımı.

1.2.3 Statistical Characterization and Generation of Fading Channel

autocorrelation $\xrightarrow{f}$ power spectral density
 öztirinti

$$\begin{aligned} \gamma_{h_I h_I}(\tau) &= E_{\tau, \theta} [h_I(t) h_I(t + \tau)] = \frac{\Omega_p}{2} E_{\theta_i} [\cos 2\pi f_i \tau] \\ &= \frac{\Omega_p}{2} E_{\theta} [\cos(2\pi f_m \tau \cos \alpha)] \end{aligned} \quad (1.42)$$

$$\gamma_{h_I h_Q}(\tau) = E_{\tau, \theta} [h_I(t) h_Q(t + \tau)] = \frac{\Omega_p}{2} E_{\theta} [\sin(2\pi f_m \tau \cos \theta)] \quad (1.43)$$

$$\boldsymbol{\tau} = [\tau_1, \tau_2, \dots, \tau_I]$$

$$\boldsymbol{\theta} = [\theta_1, \theta_2, \dots, \theta_I]$$

(1.44)

$$\Omega_p = E[h_I^2(t)] + E[h_Q^2(t)] = \sum_{i=1}^I C_i^2$$

1.2.3 Sönümlü Kanalin İstatistiksel Karakterizasyonu ve Üretimi

$\gamma_{h_I h_Q}$

$$\underline{\underline{\gamma_{h_I h_I}(\tau) = \frac{\Omega_p}{2} \int_{-\pi}^{\pi} \cos(2\pi f_m \tau \cos \theta) p(\theta) G(\theta) d\theta}}$$

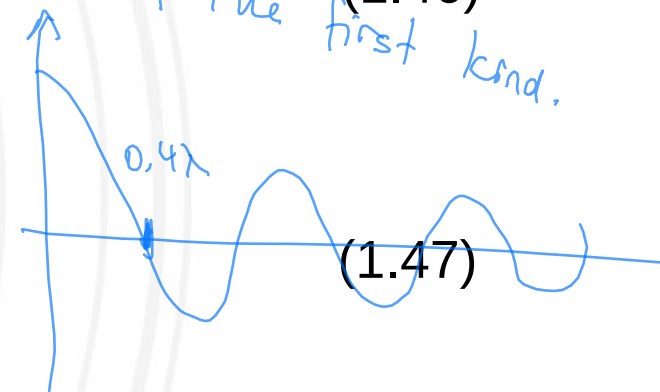
$$= \frac{\Omega_p}{2} \frac{1}{2\pi} \int_{-\pi}^{\pi} \cos(2\pi f_m \tau \cos \theta) d\theta = \frac{\Omega_p}{2} J_0(2\pi f_m \tau)$$

$\phi_i = 2\pi \{ (f_c + f_i) \frac{z_i}{c} - f_i t \}$
 $f_i = \frac{v}{\lambda} \cos \theta_i$
 (1.45)
 fast fading
 0-2π
 bessel function of the zeroth order of the first kind.

$$\gamma_{h_I h_Q}(\tau) = \frac{\Omega_p}{2} \frac{1}{2\pi} \int_{-\pi}^{\pi} \sin(2\pi f_m \tau \cos \theta) d\theta = 0$$

$$\gamma_{\tilde{y}\tilde{y}}(\tau) = \gamma_{h_I h_I}(\tau) \cos 2\pi f_c \tau - \gamma_{h_I h_Q} \sin 2\pi f_c \tau$$

$$= \frac{\Omega_p}{2} J_0(2\pi f_m \tau) \cos 2\pi f_c \tau$$



1.2.3 Sönümlü Kanalin İstatistiksel Karakterizasyonu ve Üretimi

- Klasik Doppler spektrumu

$$\underline{S_{h_I h_I}(f)} = \underline{S_{h_Q h_Q}(f)} = \underline{F[\gamma_{h_I h_I}(t)]} = \begin{cases} \frac{\Omega_p}{2\pi f_m} \frac{1}{\sqrt{1 - (f/f_m)^2}} & |f| \leq f_m \\ 0 & \text{otherwise} \end{cases} \quad (1.48)$$

Handwritten notes: $\sum C_i^2$ (pointing to Ω_p), doppler kayman (pointing to the denominator)

$$\begin{aligned} \gamma_{hh}(\tau) &= \frac{1}{2} E[h^*(t)h(t+\tau)] \\ &= \gamma_{h_I h_I}(\tau) + j\gamma_{h_I h_Q}(\tau) \end{aligned} \quad (1.49)$$

$$S_{hh}(f) = S_{h_I h_I}(f) + jS_{h_I h_Q}(f) \quad (1.50)$$

1.2.3 Sönümlü Kanalin İstatistiksel Karakterizasyonu ve Üretimi

$$\gamma_{\tilde{y}\tilde{y}}(\tau) = \text{Re} \left[\gamma_{hh}(\tau) e^{j2\pi f_c \tau} \right] \quad (1.51)$$

$$\text{Re}[a] = \frac{a + a^*}{2} \quad (1.52)$$

$$\gamma_{hh}(\tau) = \gamma_{hh}^*(-\tau) \quad (1.53)$$



$$\underline{\underline{S_{\tilde{y}\tilde{y}}(f)}} = \frac{1}{2} \left[S_{hh}(f - f_c) + S_{hh}(-f + f_c) \right] = \begin{cases} \frac{\Omega_p}{4\pi f_m} \frac{1}{\sqrt{1 - \left(\frac{f - f_c}{f_m} \right)^2}} & |f - f_c| \leq f_m \\ 0 & \text{otherwise} \end{cases} \quad (1.54)$$

1.2.3 Sönümlü Kanalin İstatistiksel Karakterizasyonu ve Üretimi

$$S_{\tilde{y}\tilde{y}}(f)|df| = \frac{\Omega_p}{4\pi} \{G(\theta)p(\theta) + G(-\theta)p(-\theta)\} |d\theta| \quad (1.55)$$

$$|df| = f_m |-\sin \theta d\theta| = \sqrt{f_m^2 - (f - f_c)^2} |d\theta| \quad (1.56)$$

$$S_{\tilde{y}\tilde{y}}(f) = \frac{\Omega_p/4}{\sqrt{f_m^2 - (f - f_c)^2}} \{G(\theta)p(\theta) + G(-\theta)p(-\theta)\} \quad (1.57)$$

1.2.3 Sönümlü Kanalın İstatistiksel Karakterizasyonu ve Üretimi

■ Rice sönümlenmesi

(güçlü Line of Sight bileşeni)

$$p(\theta) = \frac{1}{K+1} \tilde{p}(\theta) + \frac{K}{K+1} \delta(\theta - \theta_0)$$

Scattering component

LoS component

$$K = \frac{c^2}{2\sigma^2}$$

$$\gamma_{h_t h_r}(\tau) = \frac{1}{K+1} \frac{\Omega_p}{2} J_0(2\pi f_m \tau) + \frac{K}{K+1} \frac{\Omega_p}{2} \cos(2\pi f_m \tau \cos \theta)$$

itinkeli kanal

Jakes modeli
Clark modeli
F.W.G.N

Rayleigh: (1.58)

$w_1 \sim \mathcal{W}(0, \sigma)$ iid.

$w_2 \sim \mathcal{W}(0, \sigma)$ Gaussian

$$X = w_1 + jw_2 \quad (1.59)$$

Rice

$$X = c + w_1 + jw_2 \quad (1.60)$$

Single shot

Zaman serisi elde etmek için

Doppler spektrumu

1.2.3 Statistical Characterization and Generation of Fading Channel

$$\gamma_{h_I h_Q}(\tau) = \frac{K}{K+1} \frac{\Omega_p}{2} \sin(2\pi f_m \tau \cos \theta) \quad (1.61)$$

$$S_{hh}(f) = \frac{1}{K+1} S_{hh}^c(f) + \frac{K}{K+1} S_{hh}^d(f)$$
$$= \begin{cases} \frac{1}{K+1} \frac{\Omega_p}{2\pi f_m} \frac{1}{\sqrt{1-(f/f_m)^2}} + \frac{K}{K+1} \frac{\Omega_p}{2} \delta(f - f_m \cos \theta_0) & |f| \leq f_m \\ 0 & \text{otherwise} \end{cases} \quad (1.62)$$